Master's Thesis of Soumya Chatterjee

Mentoring:

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Introduction

Understanding trip purposes is essential for effective urban planning and transportation management. GPSbased travel diaries offer precise trip data but lack context regarding trip purposes. This research integrates machine learning and rule-based models to enhance trip purpose prediction using GPS data. The study area is Munich Metropolitan area.

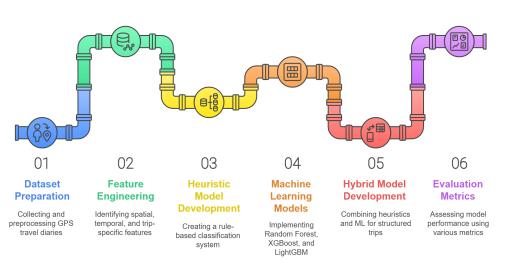
Research Objectives

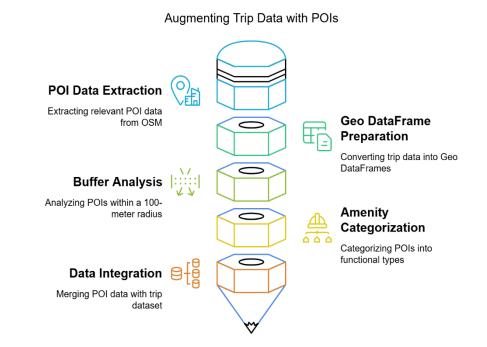
- Develop trip purpose prediction models using the Mobilität.Leben dataset.
- Integrate external data sources (land use, POI data) for improved accuracy.
- Compare heuristic, machine learning, and hybrid approaches.
- Balance model interpretability and prediction accuracy.

External Data Integration

Integrating Land Use Data with QGIS المللم **Retrieve Land** Assign Land Use Data Use Land use data is Categories retrieved for a Spatial subset of trips Each trip endpoint is providing contextual 0 Intersection assigned a land use information. category based on The OSM plugin the intersecting **Upload Trip** conducts a sp atial polygon. Endpoints intersection of trip points with land use Coordinates of trip polygons endpoints are uploaded to QGIS as a point lay **Methodology**

Model Development Process for GPS Data





Results & Conclusions

- **Heuristic Model:** High accuracy for structured trips (Home: 79.48%, Shopping: 76.85%), but poor for flexible trips (Medical: 25.71%).
- **LightGBM Model:** Improved classification (Overall Accuracy: 72.63%), better recognition of commuting patterns, but challenges with overlapping categories.
- **Hybrid Model:** Best performance (Overall Accuracy: 83.15%), significantly improved non-routine trip classification.
- Hybrid model successfully balances accuracy and interpretability.
- Incorporate real-time mobility data and address ethical considerations in GPS data analysis.



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